

ASME HST-1–2023

(Revision of ASME HST-1–2017)

Performance Standard for Electric Chain Hoists

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AN AMERICAN NATIONAL STANDARD



**The American Society of
Mechanical Engineers**

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Mechanical Engineers

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FOREWORD

ASME HST-1 is one in a series of standards that provides performance requirements for hoists. Originally published in 1982, ASME HST-1 was developed by the ASME HST Standards Committee, Hoists — Overhead to guide manufactures, purchasers, and users of electric chain hoists.

Standards in the ASME HST series are as follows:

Designator	Title
ASME HST-1	Performance Standard for Electric Chain Hoists
ASME HST-2	Performance Standard for Hand Chain Manually Operated Chain Hoists
ASME HST-3	Performance Standard for Lever Hoists
ASME HST-4	Performance Standard for Overhead Electric Wire Rope Hoists
ASME HST-5	Performance Standard for Air Chain Hoists
ASME HST-6	Performance Standard for Air Wire Rope Hoists

ASME HST-1-2023 includes a [Nonmandatory Appendix A](#) that provides the U.S. Department of Defense requirements for electric chain hoists used in marine and other applications. [Nonmandatory Appendix A](#), in conjunction with ASME HST-1, has replaced the requirements of MIL-H-15317.

ASME HST-1-2023 includes a [Nonmandatory Appendix B](#) that provides guidance to assist both the manufacturer and the end user in configuring a hoist for use in a potentially explosive environment. The requirements of this Standard shall be applied with the requirements of ASME B30.16.

This Standard is available for public review on a continuing basis. Public review provides an opportunity for additional input from industry, academia, regulatory agencies, and the public-at-large.

ASME HST-1-2023 was approved by the American National Standard Institute as an American National Standard on April 6, 2023.

ASME HST COMMITTEE

Hoists — Overhead

(The following is the roster of the committee at the time of approval of this Standard.)

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Revisions and Errata. The committee processes revisions to this Standard on a continuous basis to incorporate changes that appear necessary or desirable as demonstrated by the experience gained from the application of the Standard. Approved revisions will be published in the next edition of the Standard.

In addition, the committee may post errata on the committee web page. Errata become effective on the date posted. Users can register on the committee web page to receive e-mail notifications of posted errata.

This Standard is always open for comment, and the committee welcomes proposals for revisions. Such proposals should be as specific as possible, citing the paragraph number(s), the proposed wording, and a detailed description of the reasons for the proposal, including any pertinent background information and supporting documentation.

Cases

(a) The most common applications for cases are

(1) to permit early implementation of a revision based on an urgent need

(2) to provide alternative requirements

(3) to allow users to gain experience with alternative or potential additional requirements prior to incorporation directly into the Standard

(4) to permit the use of a new material or process

(b) Users are cautioned that not all jurisdictions or owners automatically accept cases. Cases are not to be considered as approving, recommending, certifying, or endorsing any proprietary or specific design, or as limiting in any way the freedom of manufacturers, constructors, or owners to choose any method of design or any form of construction that conforms to the Standard.

(c) A proposed case shall be written as a question and reply in the same format as existing cases. The proposal shall also include the following information:

(1) a statement of need and background information

(2) the urgency of the case (e.g., the case concerns a project that is underway or imminent)

(3) the Standard and the paragraph, figure, or table number(s)

(4) the edition(s) of the Standard to which the proposed case applies

(d) A case is effective for use when the public review process has been completed and it is approved by the cognizant supervisory board. Approved cases are posted on the committee web page.

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ASME HST-1-2023

SUMMARY OF CHANGES

Following approval by the ASME HST Committee and ASME, and after public review, ASME HST-1-2023 was approved by the American National Standards Institute on April 6, 2023.

ASME HST-1-2023 includes the following changes identified by a margin note, **(23)**.

Page	Location	Change
1	Section 1-0.1	Subparagraph (b)(6) revised
1	Section 1-0.2	Definitions of <i>abnormal operating conditions</i> ; <i>brake</i> , <i>mechanical load</i> ; <i>braking</i> , <i>dynamic</i> ; <i>control actuator</i> ; <i>lift</i> ; <i>power transmission parts</i> ; <i>qualified person</i> ; and <i>stop-start control function</i> revised
4	Section 1-0.4	Last paragraph added
6	Table 1-1.3-1	(1) General Notes (a) and (b) and Note (1) revised (2) Former Note (1) redesignated as General Note (c)
8	Table 1-1.6-1	Notes (1) and (2) revised
10	Chapter 1-2	(1) Added (2) Former Section 1-1.8 redesignated as Section 1-2.2
11	Chapter 1-3	(1) Added (2) Former para. 1-1.7.5 and Section 1-1.9 redesignated as Section 1-3.6 and para. 1-3.3.4, respectively
14	Chapter 1-4	(1) Former Section 1-1.10 redesignated as Chapter 1-4 (2) Form 1-4.1-1 (formerly Form 1-1.10-1) revised
16	Nonmandatory Appendix A	In-text reference citations updated throughout
16	A-1.4	Updated
17	A-2	(1) Paragraphs A-2.2 and A-2.6 through A-2.8 revised (2) Paragraph A-2.3.1 editorially redesignated as A-2.3 (3) First paragraph of A-2.4 editorially redesignated as A-2.4.1, and former A-2.4.1 redesignated as A-2.4.2
19	Table A-2.8-1	SI values added
19	A-3.2	Revised
20	A-3.3.5	Last sentence added
20	A-3.6.1	Paragraphs A-3.6.1.1 and A-3.6.1.3 revised
21	A-3.9.6	Added
22	A-3.10	Revised
22	A-4.1	First paragraph editorially redesignated as A-4.1.1, and former A-4.1.1 redesignated as A-4.1.2
23	A-4.2.8	Added
23	A-5.1.1	Revised
23	A-5.1.2	In paras. A-5.1.2.1 and A-5.1.2.2, last sentence added
25	A-5.1.12	Last sentence added

<i>Page</i>	<i>Location</i>	<i>Change</i>
25	A-5.1.13	Added
25	A-5.2	(1) Paragraph A-5.2.1 editorially redesignated as A-5.2 (2) Subparagraph (d) added and subsequent subparagraphs redesignated
25	A-5.3	Paragraph A-5.3.1 editorially redesignated as A-5.3
25	A-6	Former para. A-5.3.2 revised and redesignated as A-6
29	Nonmandatory Appendix C	Added

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Chapter 1-0

Scope, Definitions, References, and Appendices

SECTION 1-0.1: SCOPE

(23)

(a) This Standard establishes performance requirements for electric chain hoists for vertical lifting service involving material handling of freely suspended (i.e., unguided) loads using load chain of the roller or welded link types with one of the following types of suspension:

- (1) lug
- (2) hook or clevis
- (3) trolley

(b) This Standard is applicable to hoists manufactured after the date on which this Standard is issued. It is not applicable to

- (1) damaged or malfunctioning hoists
- (2) hoists that have been misused or abused
- (3) hoists that have been altered without authorization of the manufacturer or a qualified person
- (4) hoists used for lifting or supporting people
- (5) hoists used for the purpose of drawing both the load and the hoist up or down the hoist's own load chain or chains
- (6) hoists used for marine and other applications as required by the U.S. Department of Defense (DOD) unless

Nonmandatory Appendix A is invoked.

The requirements of this Standard shall be applied together with the requirements of ASME B30.16. Please also refer to ASME B30.16 for requirements pertaining to marking, construction, and installation; inspection, testing, and maintenance; and operation.

SECTION 1-0.2: DEFINITIONS

(23)

abnormal operating conditions: environmental ambient conditions that are unfavorable, harmful, or detrimental to the operation of a hoist, such as excessively high or low temperature, exposure to weather, corrosive fumes, dust laden or moisture laden atmospheres, and hazardous locations.

ambient temperature: the temperature of the atmosphere surrounding the hoist.

beam: an overhead standard structural or specially fabricated shape on which the trolley operates.

brake: a device, other than a motor, used for retarding or stopping motion by means of friction or power.

brake, holding: a friction brake for a hoist that is automatically applied and prevents motion when power is off.

brake, mechanical load: an automatic type of friction brake used for controlling loads in a lowering direction. This unidirectional device requires torque from the motor to lower a load but does not impose any additional load on the motor when lifting a load. This mechanical brake may also be used as a holding brake if designed as such by the manufacturer.

braking, control: a method of controlling speed by removing energy from the moving body or by imparting energy in the opposite direction.

braking, dynamic: a method of controlling speed by using the motor as a generator, with the energy being dissipated by resistance.

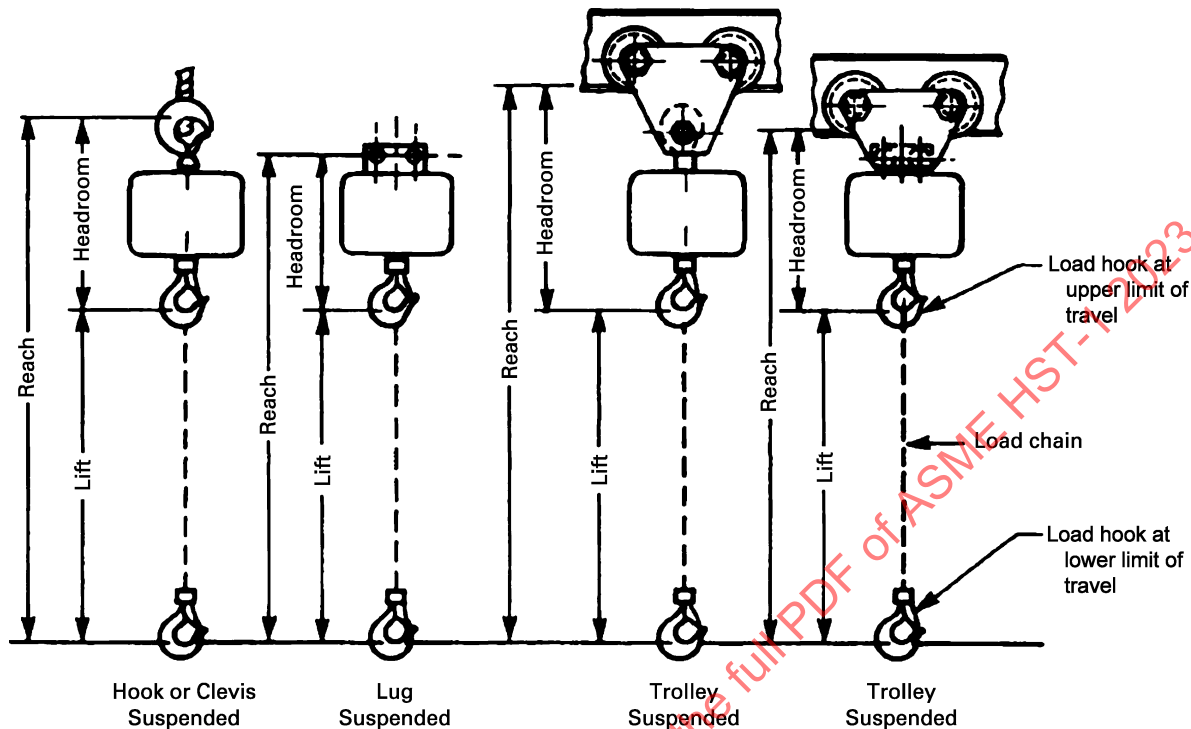
braking, mechanical: a method of controlling or reducing speed by friction.

braking, regenerative: a method of controlling speed in which the electrical energy generated by the motor is fed back into the power system.

chain, load: the load-bearing chain in a hoist.

chain, roller: a series of alternately assembled roller links and pin links in which pins articulate inside the bushings, and the rollers are free to turn on the bushings. Pins and bushings are press-fit in their respective link plates.

Figure 1-0.2-1
Headroom, Lift, and Reach



chain, welded link: a chain consisting of a series of interwoven links formed and welded.

NOTE: Load chain properties do not conform to those shown in ASME B29.1 or ASME B30.9.

contactor: an electromechanical device for opening and closing an electric power circuit.

control actuator: a manual means at the operating station by which hoist or trolley controls are energized.

control enclosure: the housing containing the electrical control components.

cushioned start: an electrical or mechanical method for reducing the rate of acceleration of trolley motion.

hazardous (classified) locations: locations where fire or explosion hazards may exist. Locations are classified depending on the properties of the flammable vapors, liquids or gases, or combustible dusts or fibers that may be present and the likelihood that a flammable or combustible concentration or quantity is present. Refer to NFPA 70.

headroom: headroom is measured with the load hook at its upper limit of travel and is the distance from the saddle of the load hook to the following locations (see Figure 1-0.2-1):

- saddle of the top hook on hook suspended hoists
- centerline of the suspension holes on lug suspended hoists
- wheel tread line on trolley suspended hoists

hoist: a machinery unit that is used for lifting or lowering a freely suspended (i.e., unguided) load.

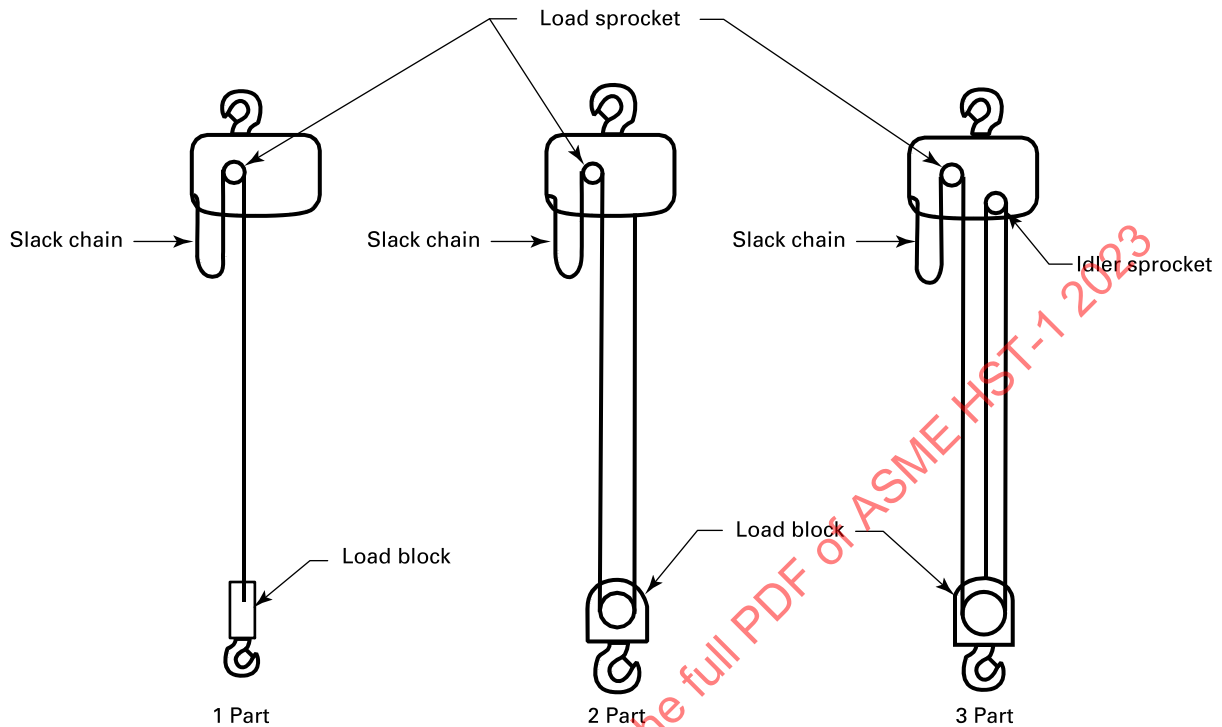
hoist speed: the rate of motion that the load hook obtains while lifting a rated load.

hook suspended: suspension of hoist from a trolley or rigid structure by means of a hook at top of hoist.

idler sprocket: a freely rotating device that changes the direction of the load chain. This device is sometimes called an idler wheel, idler sheave, pocket wheel, or chain wheel (see Figure 1-0.2-2).

lift: the maximum vertical distance through which the load hook can travel; the total hook movement between its upper limit of travel and its position at its lower limit of travel (see Figure 1-0.2-1).

**Figure 1-0.2-2
Reeving**



lifting devices, below-the-hook: devices that are not normally reeved onto the hoist chains, such as hook-on buckets, magnets, grabs, and other supplemental devices used for handling certain types of loads. The weight of these devices shall be considered part of the load to be lifted.

limit device: a device that limits equipment motion or takes control of particular functions without action of the operator when a limiting condition is reached.

load, rated (capacity): maximum load designated by the manufacturer for which the hoist is designed and built.

load, working: the external load applied to the hoist, including the weight of load-attaching equipment such as shackles and slings.

load block: the assembly of hook or shackle, swivel, bearing, pins, sprocket, and frame suspended by the load chain. This shall include all appurtenances reeved in the load chain.

load chain container: a device used to collect the slack load chain.

load hook: the hook used to connect the load to the hoist.

load sprocket: a hoist component that transmits motion to the load chain. This component is sometimes called a load wheel, load sheave, pocket wheel, chain wheel, or lift wheel (see Figure 1-0.2-2).

load suspension parts: the means of suspension (hook or lug), the structure or housing that supports the load sprocket, the load chain, the sprockets, and the load block or hook.

lug suspended: suspension of the hoist from a trolley or permanent structure by means of one or more bolts or pins through a rigid- or swivel-type lug.

magnetic control: a means of controlling the direction and speed of the hoist and trolley by using magnetic contactors and relays.

minimum radius: the smallest radius of the beam, measured to the centerline of the web of the beam, on which the trolley will operate.

normal operating conditions: conditions during which a hoist is performing functions within the scope of the original design.

overload: any load greater than the rated load.

parts (lines): number of lines of chain supporting the load block or hook.

pendant station: electrical controls suspended from the hoist for operating the unit from the floor.

power transmission parts: machinery components, including the gears, shafts, clutches, couplings, bearings, motors, and brakes.

qualified person: a person who, by possession of a recognized degree in an applicable field or a certificate of professional standing, or by extensive knowledge, training, and experience, has successfully demonstrated the ability to solve or resolve problems relating to the subject matter and work.

rated frequency: the electrical operating frequency listed on the hoist nameplate or the hoist motor nameplate.

reach: the distance from the saddle of the load hook at its lower limit of lift to the upper point of the headroom measurement. Reach is equal to lift plus headroom (see [Figure 1-0.2-1](#)).

reeving: a system in which a chain travels around sprockets (see [Figure 1-0.2-2](#)).

shall: a word indicating a requirement.

should: a word indicating a recommendation.

stop-start control function: a control function used to close and open a mainline contactor that provides or removes line power to or from all other function contactors. Normally, the control function does not remove power from the control circuit or pendant station. Also called “off-on” or “power off-power on” control function.

NOTE: When a powered-below-the-hook device is being used with the hoist, where removing power from the lifting device would result in a load drop, this stop-start control function shall not remove power from the lifting device.

switch: a device for making, breaking, or changing the connections in an electric circuit.

trolley: a wheeled mechanism from which a hoist is suspended to provide horizontal motion of the hoist along a beam.

trolley speed: the rate of motion that a motor-operated trolley (and hoist) obtains while traveling along a beam.

trolley suspended: suspension of a hoist from a trolley. The hoist can be connected to the trolley by hook, clevis, or lug suspension, or the hoist can be integral with the trolley.

SECTION 1-0.3: REFERENCES

The following is a list of publications referenced in this Standard. The latest edition shall apply.

ANSI/NEMA MG 1. Motors and Generators. National Electrical Manufacturers Association.

ASME B29.1. Precision Power Transmission Roller Chains, Attachments, and Sprockets. The American Society of Mechanical Engineers.

ASME B30.9. Slings. The American Society of Mechanical Engineers.

ASME B30.16. Overhead Underhung and Stationary Hoists. The American Society of Mechanical Engineers.

NEMA ICS-6. Industrial Control And Systems: Enclosures. National Electrical Manufacturers Association.

NFPA 70. National Electrical Code. National Fire Protection Association.

(23) SECTION 1-0.4: APPENDICES

[Nonmandatory Appendix A](#) applies to the performance requirements for hoists used in marine and other applications. The requirements stated in [Nonmandatory Appendix A](#) are in addition to the requirements of ASME HST-1 and ASME B30.16 and must be invoked separately.

[Nonmandatory Appendix B](#) includes examples of hoist applications as an aid to users in making the selection of the proper hoist for the application.

[Nonmandatory Appendix C](#) applies to hoists used in locations defined as hazardous (potentially explosive) locations. The guidance provided in [Nonmandatory Appendix C](#) is in addition to the requirements of ASME HST-1.

Chapter 1-1

Performance

SECTION 1-1.1: GENERAL

All equipment selected in accordance with this Standard is designed to perform satisfactorily when used in accordance with ASME B30.16, Chapters 16-2 through 16-4 and used within the rated load and hoist duty service classification. All equipment shall provide speeds, lifts, and headroom in accordance with the manufacturer's specifications or specifications agreed upon by the manufacturer and the user.

SECTION 1-1.2: HOIST DUTY SERVICE CLASSIFICATION

Service conditions have an important influence on the performance of the wearing parts of a hoist, such as gears, bearings, load chain, sprockets, electrical equipment, brake linings, load and lift limiting devices, and wheels. Careful consideration of the hoist duty service classifications described in this Section will enable the user to evaluate the application and obtain a hoist designed for optimum performance and minimum maintenance. If doubt exists regarding hoist selection, the hoist supplier should be consulted. Many factors enter into the selection of the proper hoist to perform a given function. Hoisting equipment consists of both mechanical and electrical components, and both must be considered when analyzing the service the hoist must perform.

The factors that influence the mechanical and electrical performance of any hoist include the following:

(a) *Load Distribution.* The actual distribution or proportion of full and partial loads to be handled by the equipment, including lifting devices, has an important effect on the life of power transmission components. For example, ball-bearing life varies according to the cube of the load. A 2-ton (1 814.4-kg) hoist operated at a mean effective load of 1 ton (907.2 kg) will have a ball-bearing life eight times that of the same hoist used steadily at its rated load.

(b) *Operational Time.* Operational time is the total running time of the hoist per hour or per work period.

(c) *Work Distribution.* This is determined by whether the operational time is uniformly distributed over the work period or concentrated in a short time span. Work distribution generally does not appreciably affect mechanical wear, but does materially affect the electrical components such as motors, brakes, and controls. For example, a hoist motor designed to operate 15 min out of each hour of an 8-hr shift cannot handle 2 hr of steady run and 6 hr of idle time even though either condition requires only 2 hr of operational time per 8-hr shift.

(d) *Number of Starts and Stops.* This directly affects all electromechanical devices, such as motors, contactors, brakes, and solenoids.

(e) *Repetitive Long Lowering Operations.* Such operations generate heat in control braking means.

(f) *Environmental Conditions.* Hoist equipment is designed to operate in ambient temperatures between 0°F and 104°F (–18°C and 40°C) and in atmospheres reasonably free from dust, moisture, and corrosive fumes unless otherwise specified.

(g) *Hazardous Locations.* If hoists are used in hazardous locations as defined by NFPA 70 or other special codes, modifications or additional precautions not covered by this Standard may be required. In these locations, only hoists designed in a manner suitable for the conditions encountered shall be used.

SECTION 1-1.3: DUTY CLASSIFICATION

While all the factors listed in [Section 1-1.2](#) shall be considered in selecting the proper class of hoist, most industrial applications, having randomly distributed loads or uniform loads up to 65% of rated load handled periodically throughout the work period, can be generalized according to the type of workshop or area of application. Listed in Column 1 of [Table 1-1.3-1](#) are the three duty classes that have been established for electric chain hoists. In Column 2 are listed typical areas of application where each class can normally be applied. The majority of hoist applications will fall into one of the two categories, H2 or H3, and the use of the generalized description in Column 2 of [Table 1-1.3-1](#) for selection of the hoist will be adequate.

(23)

Table 1-1.3-1
Duty Classifications

Hoist Duty Class (Column 1)	Typical Areas of Application (Column 2)	Operational Time Ratings at $K = 0.65$ [Note (1)]			
		Uniformly Distributed Work Periods		Infrequent Work Periods	
		Max. On Time, min/hr (Column 3)	Max. No. of Starts/hr (Column 4)	Max. On Time From Cold Start, min (Column 5)	Max. No. of Starts (Column 6)
H2	Light machine shop, fabricating service, and maintenance. Loads and utilization randomly distributed. Rated loads infrequently handled.	7.5 (12.5%)	75	15	100
H3	General machine shop, fabricating, assembly, storage, and warehousing. Loads and utilization randomly distributed.	15 (25%)	150	30	200
H4	High-volume handling in steel warehouses, machine shops, fabricating plants and mills, and foundries. Manual or automatic cycling operations in heat treating and plating. Loads at or near rated load frequently handled.	30 (50%)	300	30	300

GENERAL NOTES:

- (a) *Two-Speed Operation.* Unless otherwise specified by the hoist manufacturer, electric chain hoists should not be operated at low speed for more than one-third of the maximum on time for any duty classification. Also, the end user should consider each transition from low to high speed or high to low speed to be a motor start when calculating the maximum number of starts per hour. For slow-speed operation beyond one-third of maximum on time, consult the hoist manufacturer.
- (b) *Variable-Speed Operation.* For this Standard, variable-speed operation is categorized as follows:
- (1) slow speed: operation at 25% to 50% of rated frequency
 - (2) normal speed: operation at 50% to 100% of rated frequency
 - (3) overspeed: operation above 100% of rated frequency

Unless otherwise specified by the hoist manufacturer, slow-speed operation of variable frequency drive–equipped electric chain hoists should be limited to no more than one-third of the maximum on time for any duty classification. For regular operating speeds below 25% of rated frequency, low-speed operation beyond one-third of the maximum on time, or overspeed operation, consult the hoist manufacturer. For calculation of the maximum number of starts per hour, a motor start is the starting of the motor from a stationary state. Any instances of starting the motor from a nonstationary state should not be considered in the calculation.

- (c) See paras. 1-1.3.1 and 1-1.3.2.

NOTE: (1) K = mean effective load factor.

1-1.3.1 Operational Time Ratings

If in doubt as to the required duty classification for an application, refer to the data in Columns 3 through 6 of Table 1-1.3-1, which show the operational time ratings for each class.

(a) *Uniformly Distributed Work Periods*

(1) *Maximum On Time in Minutes per Hour (Column 3).* The maximum running time in minutes per hour permitted for duty class when hoist utilization is uniformly distributed over a given work period.

(2) *Maximum Number of Starts per Hour (Column 4).* The maximum number of motor starts per hour permitted for the duty class when hoist utilization is uniformly distributed over a given work period.

(b) *Infrequent Work Periods*

(1) *Maximum On Time From Cold Start in Minutes (Column 5).* The maximum total running time for hoist utilization for the duty class starting with hoist at ambient temperature. These values cover infrequent periods of extended use and are applicable only with hoist at ambient temperature and cannot be repeated unless hoist is allowed to cool down to ambient temperature between periods. Typical examples would include setting machinery in place, unloading a truckload of steel, filling a stock order from a stock room, etc.

(2) *Maximum Number of Starts (Column 6).* The maximum total number of motor starts permitted for infrequent work periods specified in Column 5.

1-1.3.2 Mean Effective Load

Mean effective load denotes a theoretical single load value that has the same effect on the hoist as various loads actually applied to the hoist over a specified period of time. K is the mean effective load factor and is expressed as

$$K = \sqrt[3]{W_1^3 P_1 + W_2^3 P_2 + W_3^3 P_3 \dots W_n^3 P_n}$$

where

- K = mean effective load factor. Mean effective load factor is the ratio of mean effective load to rated load.
- P = load probability. Load probability is the ratio of running time under each load magnitude condition to the hoist total running time. The sum total of all load probabilities used in the above equation must equal 1.0.
- W = load magnitude. Load magnitude is the ratio of the hoist operating load to the hoist rated load. Operation with no load shall be included along with the weight of any dead load, such as device lifting attachments.

1-1.3.3 Randomly Distributed Loads

Randomly distributed implies that loads applied to the hoist are assumed to be evenly distributed within the rated load of the hoist in decreasing steps of 20% of the previous load value. Randomly distributed loads are, therefore, considered as 100%, 80%, 64%, 51%, 41%, 33%, 26%, etc., of rated load. Operation with randomly distributed loads is considered on an equal-time basis for the operating time remaining after accounting for the time the hoist is operating at no load and with rated load. Randomly distributed loads will result in a mean effective load factor of 0.65.

SECTION 1-1.4: APPLICATION ANALYSIS

1-1.4.1 General

(a) If the operation consists of lowering loads over long distances of more than 50 ft (15 m), the mechanical load brake heat dissipation capability (overheating) may become a factor. Consult manufacturer for particulars.

(b) Motor heating generated by the number of starts is not appreciably affected by the load on the hook, and therefore the limits imposed by Columns 3 through 6 of [Table 1-1.3-1](#) are applicable for the motor regardless of the load being handled.

1-1.4.2 Fundamental Application Analysis

It is not necessary to perform a detailed application analysis or calculate mean effective load factor if all of the following conditions are met:

- (a) The hoist is operating at no load during one-half of its operating time (load probability equals 0.5).
- (b) The hoist is operating with rated load for a period of time not exceeding 20% of its operating time (load probability equal to or less than 0.2).
- (c) Other loads applied to the hoist during the remainder of its operating time are randomly distributed.

Conditions wherein the operating criteria in (a) through (c) are met will result in a mean effective load factor of 0.65 or less. If any one of these conditions cannot be met, or if a below-the-hook lifting device is attached to the load hook, a detailed application analysis using a calculated mean effective load factor should be conducted.

1-1.4.3 Detailed Application Analysis

The following general method may be used to make a detailed application analysis. Several examples of this detailed analysis method are given in [Nonmandatory Appendix B](#).

- (a) Select a hoist class from [Table 1-1.3-1](#) based on the general descriptions given in Column 2.
- (b) Select a hoist with a rated load equal to or greater than the maximum load to be lifted.
- (c) Using the information in Columns 3 through 6, select the hoist speed that will meet the operational time ratings for hoist duty class.
- (d) Determine the value of K . If $K > 0.65$, select a hoist with a higher rated load rating and recalculate K to make sure $K \leq 0.65$.
- (e) If the operational time values requirements in [Table 1-1.3-1](#) cannot be met with a K value equal to or less than 0.65, contact the manufacturer.

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**Table 1-1.6-1
Typical Hoist and Motorized Trolley Speeds**

Rated Load		Hoist Speed, ft/min (m/min) [Note (3)]	Motorized Trolley Speed, ft/min (m/min) [Note (3)]
ton (kg) [Note (1)]	tonne (kg) [Note (2)]		
$\frac{1}{8}$ (114)	$\frac{1}{8}$ (125)	16–64 (5–20)	30–100 (9–30)
$\frac{1}{4}$ (227)	$\frac{1}{4}$ (250)	7–64 (2–20)	30–100 (9–30)
$\frac{1}{2}$ (454)	$\frac{1}{2}$ (500)	7–64 (2–20)	30–100 (9–30)
1 (908)	1 (1 000)	7–64 (2–20)	30–100 (9–30)
$1\frac{1}{2}$ (1 361)	$1\frac{1}{2}$ (1 500)	4–40 (1–12)	30–100 (9–30)
2 (1 815)	2 (2 000)	4–40 (1–12)	30–100 (9–30)
3 (2 722)	3 (3 000)	4–40 (1–12)	30–100 (9–30)
4 (3 629)	4 (4 000)	4–24 (2–7)	30–100 (9–30)
≥ 5 (≥ 4 536)	≥ 5 (≥ 5 000)	4–24 (2–7)	30–100 (9–30)

GENERAL NOTES:

- (a) Hoist and trolley speeds should be determined by an analysis of the number and length of cycles required for the work period.
- (b) For trolley speeds above 100 ft/min (30 m/min) or for use on beams with curved sections, it is recommended that a cushioned start or multispeed drive be specified.
- (c) In applications requiring close load spotting for hoist or trolley, refer to manufacturer for reduced speed or multiple speed control.

NOTES:

- (1) 1 ton = 2,000 lb
- (2) 1 tonne = 1 000 kg
- (3) Ranges shown are for single-speed hoists and trolleys.

SECTION 1-1.5: SPECIFICATION OF LIFT, HEADROOM, AND REACH**1-1.5.1 Lift**

Most electric chain hoists are manufactured with standard lifts of 10 ft, 15 ft, and 20 ft (3.1 m, 4.6 m, and 6.1 m). One of these standard lifts will normally be adequate for the particular requirement. It is recommended that the purchaser specify the required lift on the inquiry or bid request.

1-1.5.2 Headroom

Headroom should be specified if it is important to the application.

1-1.5.3 Reach

Reach should be specified if it is important to the application.

SECTION 1-1.6: SPEEDS: HOIST AND TROLLEY

Hoisting equipment is available over a wide range of hoist and trolley speeds. Listed in Table 1-1.6-1 are typical speed ranges commonly available. Hoist and trolley speeds may vary $\pm 10\%$ from the specified speed.

NOTE: Table 1-1.6-1 is to be used as a guide only and is not intended to restrict either the manufacturer or the buyer from offering or specifying speeds outside the ranges shown, nor should it be inferred that speeds above or below the range shown are not compatible with the required class of hoist.

SECTION 1-1.7: TROLLEYS

Hoist trolleys are available in plain, hand-chain-operated, and motor-driven types. Selection of each type depends upon the application.

1-1.7.1 Plain Trolleys

This type is recommended where trolley motion is infrequent or relatively short. Due to the required force to manually operate this type of trolley, it is also recommended that use of plain trolleys be limited to a maximum load of 3 tonnes (3 000 kg) with the elevation of the beam not more than 20 ft (6 m) above the operator's floor level.

1-1.7.2 Hand-Chain-Operated Trolleys

Motion is obtained by pulling on the hand chain that is connected to trolley wheels through gears or sprockets. This type is recommended where trolley motion is relatively infrequent or short, and especially for those loads and beam heights where a plain-type trolley would be impractical.

The hand-chain-operated trolley provides good load spotting ability.

The hand chain shall be guarded to prevent hand chain disengagement from the hand chain wheel.

The hand chain shall withstand, without permanent distortion, a force of 3 times the pull required to traverse the trolley with rated load.

1-1.7.3 Motor-Driven Trolleys

This type is recommended where operating frequency, distance of travel, or the type of load to be handled would cause unsatisfactory operation if the trolley were of the plain or hand-chain-operated type. Design of motor-driven trolleys shall be based on intermittent operation on a straight beam, unless otherwise specified. Where trolley travel involves a curved beam, beam switches, exceptionally long runs, or near continuous operation, a special design may be required. If these conditions apply, the manufacturer should be consulted.

Brakes, when specified, may be actuated by mechanical or electrical means and shall have the following characteristics:

(a) Brakes shall have sufficient capacity to stop the trolley within a distance in feet (meters) equal to 10% of the rated load speed in ft/min (m/min) when traveling at rated speed with rated load.

(b) Brakes shall have heat-dissipation capability for the specified frequency of operation.

(c) Brakes shall have provision for adjustment where necessary to compensate for wear.

1-1.7.4 Trolley Wheels

When a trolley is required for use with a hoist, the type and size of support beam shall be specified to ensure the trolley wheel contour is suitable for the contour of the beam.

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Chapter 1-2 Mechanical

SECTION 1-2.1: REEVING

Hoist reeving may be one part or multiple parts. See [Figure 1-0.2-2](#) for common examples.

SECTION 1-2.2: OVERLOAD LIMITING DEVICE

An overload limiting device, when furnished, shall be designed to permit operation of the hoist within its rated load and to limit the amount of overload that can be lifted by a properly maintained hoist under normal operating conditions.

The overload limiting device may allow the lifting of an overload but shall be designed to prevent the lifting of an overload that could cause damage to the hoist. This does not imply that any overload is to be intentionally applied to the hoist.

The overload limiting device is an emergency device and shall not be used to measure the maximum load to be lifted nor to sense the overload imposed by a constrained load.

Chapter 1-3 Electrical

(23)

SECTION 1-3.1: GENERAL

All furnished electrical equipment shall conform to the applicable sections of the latest edition of NFPA 70. The user shall specify the voltage, frequency, and phase of the power supply. The supply voltage shall be maintained within $\pm 10\%$ of the rated motor voltage at the hoist with motor operating at rated load.

1-3.1.1 Hazardous Locations

When hoists are used in hazardous locations as defined by NFPA 70 or other special codes, modifications or additional safety precautions not covered by this Standard may be required. Only hoists designed for the conditions encountered shall be used in these locations.

1-3.1.2 Fungus Protection

In tropical areas or other warm and humid atmospheres, fungus growth may occur on unprotected organic materials or on accumulations of dust. There are materials and procedures that will minimize these effects. Refer to the hoist manufacturer.

SECTION 1-3.2: MOTORS

(a) Motors shall be reversible, with torque characteristics suitable for hoist or trolley service, and capable of operation at rated loads and speeds in accordance with the specified service class.

(b) Temperature rise of motors shall be in accordance with ANSI/NEMA MG 1 for the class of insulation and enclosure used. The hoist manufacturer will assume 104°F (40°C) ambient temperature unless otherwise specified by the user.

(c) All AC motors at rated frequency and all DC motors shall be capable of operation within $\pm 10\%$ of rated motor voltage, but not necessarily at rated voltage performance.

(d) Standard rated motor voltage shall be in accordance with [Table 1-3.2-1](#).

(e) For nominal system voltages other than those shown in [Table 1-3.2-1](#), the rated motor voltage should be between 95% and 100% of the nominal system voltage.

SECTION 1-3.3: CONTROLLERS

1-3.3.1 Types of Control

The following types of control are available:

(a) single-speed, squirrel-cage motor with single-speed magnetic control for use on hoists and trolleys

(b) two-speed, squirrel-cage motor with two-speed magnetic control for use on hoists and trolleys

(c) variable-speed control as follows for use on hoists and trolleys:

(1) two-to-five-step magnetic control for use on hoists with mechanical load brake and on trolleys

(2) two-to-five-step magnetic electric load brake control for use on hoists without mechanical load brake

(3) two-to-five-step magnetic counter-torque control for use on hoists without mechanical load brake

(d) single-speed, squirrel-cage motor with cushioned start for use on trolleys

(e) two-speed, squirrel-cage motor with cushioned start for use on trolleys

Other types of hoist and trolley control are available that are beyond the scope of this Standard. Consult the hoist manufacturer.

Table 1-3.2-1
Typical Rated Motor Voltages

Power Supply	Voltages		
	Nominal System	Motor Rating	Permissible Motor Operating Range
AC, single phase, 60 Hz	120	115	104–126
	240	230	207–253
AC, polyphase, 60 Hz	208	200	180–220
	240	230	207–253
	480	460	414–506
	600	575	518–632
AC, polyphase, 50 Hz	208	200	180–220
	230	220	198–242
	400	380	342–418
DC	125	115	104–126
	125	120	108–132
	250	230	207–253
	250	240	216–264

1-3.3.2 Contactors

Each magnetic control shall have contactors sized for the specified service. Reversing contactors shall be interlocked to guard against line-to-line faults.

1-3.3.3 Pendant Control

- (a) Motion control actuators shall automatically return to the “OFF” position.
- (b) The pendant control station shall be mechanically supported to protect the electrical conductors against strain.
- (c) The pendant control station shall be clearly marked to indicate the function of each actuator.
- (d) The order of control functions, unless otherwise specified and as applicable, from top to bottom should be
 - (1) stop-start (off-on, power off-power on). The “STOP” (“OFF,” “POWER OFF”) control actuator shall be red.
 - (2) hoist.
 - (3) trolley.
 - (4) other functions.
- (e) Any pendant station that might present a hazard to the operator if a ground fault occurs shall be grounded.
- (f) Unless otherwise specified, the standard pendant control shall have a cord length that will locate the pendant approximately 3 ft to 4 ft (0.91 m to 1.22 m) above the lower limit of lift.

1-3.3.4 Pull-Cord Control

Pull-cord control, when furnished, shall consist of a self-centering return-to-neutral controller or master switch for the motion of hoist or trolley. Two nonconducting pull cords with suitable handles, clearly marked for direction, shall be provided for operation of each controller or master switch. Unless otherwise specified, the standard pull-cord control shall have a cord length that will locate the control handles approximately 4 ft to 5 ft (1.22 m to 1.52 m) above the lower limit of lift.

SECTION 1-3.4: CONTROL ENCLOSURES

Control enclosures, unless otherwise specified by the user, shall be NEMA Type 1 general purpose for indoor application in accordance with NEMA ICS-6, Section ICS-1-110.

Other types of control enclosures, as defined by NEMA, include but are not limited to the following:

- (a) NEMA Type 3 for dust-tight, rain-tight, sleet (ice) resistant, outdoor enclosures
- (b) NEMA Type 3R for rainproof, sleet (ice) resistant, outdoor enclosures

- (c) NEMA Type 4 for watertight, dust-tight, indoor and outdoor enclosures
- (d) NEMA Type 4X for watertight, dust-tight, corrosion resistant, indoor and outdoor enclosures
- (e) NEMA Type 12 for industrial use, dust-tight, drip-tight, indoor enclosures
- (f) NEMA Type 7 for Class I, Groups C and D, indoor hazardous locations (explosive atmosphere)
- (g) NEMA Type 9 for Class II, Groups E, F, and G, indoor hazardous locations (explosive atmosphere)

SECTION 1-3.5: RESISTORS

Resistors, when furnished, shall have sufficient thermal capacity for the class of service specified. Enclosures for resistors shall provide means for heat dissipation and shall be installed to minimize the accumulation of combustible matter. Provision shall be made to contain broken resistor parts or molten metal.

SECTION 1-3.6: CURRENT CONDUCTOR SYSTEMS

A length of flexible power cord shall be provided unless otherwise specified. The user should contact the hoist manufacturer for special arrangements to accommodate systems such as the following for trolley suspended hoists:

- (a) flexible cable
- (b) coiled cord
- (c) festooned cable
- (d) cable reel
- (e) rigid conductor

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Chapter 1-4 Inquiry Data Form

SECTION 1-4.1: TYPICAL HOIST AND TROLLEY INQUIRY DATA

See [Form 1-4.1-1](#) and [Table 1-1.6-1](#). An editable digital copy of the form may be found at <http://go.asme.org/HSTForms>.

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Form 1-4.1-1 Typical Hoist and Trolley Inquiry Data Form

HOIST

Quantity required _____

Rated load _____ tons (_____ kg)

Lift [Note (1)] _____ ft (_____ m)

Reach _____ ft (_____ m)

Headroom _____ in. (_____ mm)

Distance from operating floor to underside of beam or to point of support:

_____ ft _____ in. (_____ mm)

Hoisting speed _____ ft/min (_____ m/min)

Type of control: ☐ Single-speed ☐ Two-speed

☐ Other _____

POWER SUPPLY

Voltage	Phase	Hertz	Control Voltage
<input type="checkbox"/> 200	3	60	<input type="checkbox"/> 24
<input type="checkbox"/> 230	3	60	<input type="checkbox"/> 115
<input type="checkbox"/> 460	3	60	<input type="checkbox"/> Other _____
<input type="checkbox"/> 575	3	60	
<input type="checkbox"/> 115	1	60	
<input type="checkbox"/> 230	1	60	
<input type="checkbox"/> _____	_____	_____	Other _____

Performance Requirements (see Chapter 1-1 and Nonmandatory Appendix B):

Average lift _____ ft (_____ m)

Number of lifts/hr _____

Number of starts/hr _____

Shift hrs/day _____

Hoist service classification H _____

Furnish complete information regarding any abnormal operating conditions. For hazardous locations, identify location classification as specified in NFPA 70, if applicable, and additional information that might impact a spark resistance assessment: _____

Type of Suspension:

☐ Lug ☐ Hook ☐ Clevis

☐ Plain trolley ☐ Hand-chain-operated trolley

☐ Motor-operated trolley

☐ Other _____

TROLLEY (See Section 1-1.7)

Travel speed _____ ft/min (_____ m/min)

☐ Trolley brake required

Type of control

☐ Single-speed ☐ Two-speed ☒ Cushioned-start

☐ Other _____

Type and size of beam _____

Width of running flange _____ in. (_____ mm)

Minimum radius of beam curves

_____ ft _____ in. (_____ m)

Clearance dimensions of interlocks, switches, or beam splices (if used) _____

Current conductor system:

☒ Flexible cable or ☐ Festooned cable

☐ Cable reel ☐ Rigid conductor ☐ Coiled cord

☐ Other _____

Type of conductors (manufacturer) _____

Location of conductors on beam (use sketch if necessary)

OPTIONAL EQUIPMENT

NOTE: (1) Refer to manufacturer's catalog for standard lift that will meet the application requirement.

NONMANDATORY APPENDIX A

PERFORMANCE REQUIREMENTS FOR ELECTRIC CHAIN HOISTS USED IN MARINE AND OTHER APPLICATIONS AS REQUIRED BY THE U.S. DEPARTMENT OF DEFENSE

(23)

A-1 GENERAL

A-1.1 Scope

This Appendix provides performance requirements beyond those cited in ASME HST-1 for electric chain hoists for use in marine and other applications as required by the U.S. Department of Defense (DOD).

This Appendix, in conjunction with ASME HST-1, has replaced the requirements of MIL-H-15317 for electric chain hoists.

A-1.2 Classification

Chain electric-powered hoists shall be of the following types, as specified [see [para. A-6\(b\)](#)]:

- (a) Type I — electric chain hoist, lug suspension, double-acting
- (b) Type II — electric chain hoist, lug suspension, single-acting
- (c) Type III — electric chain hoist, parallel or right-angle geared, or plain trolley suspension
- (d) Type IV — electric chain hoist, two-wheel tandem
- (e) Type V — electric chain hoist, hook suspension
- (f) Type VI — electric chain hoist, powered trolley

A-1.3 Definitions

brittle material: material showing less than 10% elongation in gauge length for the tensile test specimen.

continuous operation: lifting and lowering a rated load through the full hoisting range at the specified lifting and lowering speeds.

excessive wear: wear that is sufficient to impair safe operation of the hoist. The following conditions define excessive wear:

- (a) increase in chain wheel pocket dimension in excess of 10%
- (b) increase in clearance tolerance between shaft and bearing in excess of 15%
- (c) life-lubricated bearings requiring lubrication
- (d) load-brake lining reduced in excess of 50% of useful life
- (e) reduction of bar diameter of link chain in excess of 10%
- (f) reduction of wall thickness for rollers and pins of roller chain in excess of 10%
- (g) reduction in gear tooth thickness of reduction gear drive in excess of 10%

recovered materials: materials that have been collected or recovered from solid waste and reprocessed to become a source of raw materials, as opposed to virgin raw materials.

(23) A-1.4 References to Other Codes and Standards

Refer to the following publications, copies of which may be obtained from the publisher as indicated. The latest edition shall be used.

AGMA 6034. Practice for Enclosed Cylindrical Worm Gear Speed Reducers and Gear Motors. American Gear Manufacturers Association.

ASTM A48/A48M. Standard Specification for Gray Iron Castings.¹ ASTM International.

¹ Publication adopted by DOD.

ASTM A143/A143M. Standard Practice for Safeguarding Against Embrittlement of Hot-Dip Galvanized Structural Steel Products and Procedure for Detecting Embrittlement.¹ ASTM International.

ASTM B26/B26M. Standard Specification for Aluminum Alloy Sand Castings.¹ ASTM International.

ASTM B633. Standard Specification for Electrodeposited Coatings of Zinc on Iron and Steel.¹ ASTM International.

DOD-G-24508. Grease, High Performance, Multi-Purpose (Metric). U.S. Department of Defense.

MIL-DTL-167-1. Mechanical Vibrations of Shipboard Equipment (Type I — Environmental and Type II — Internally Excited). U.S. Department of Defense.

MIL-DTL-917. Detail Specification: Electric Power Equipment Basic Requirements. U.S. Department of Defense.

MIL-DTL-24441. Paint, Epoxy-Polyamide, General Specification for. U.S. Department of Defense.

MIL-DTL-24441/20. Paint, Epoxy-Polyamide, Green Primer, Formula 150, Type III. U.S. Department of Defense.

MIL-DTL-24441/21. Paint, Epoxy-Polyamide, Haze Gray Formula 151, Type III. U.S. Department of Defense.

MIL-DTL-24643. Cables, Electric, Low Smoke, for Shipboard Use, General Specification for. U.S. Department of Defense.

MIL-HDBK-781. Reliability Test Methods, Plans, and Environments for Engineering Development, Qualification, and Production. U.S. Department of Defense.

MIL-PRF-24635. Coating Systems, Weather-Resistant, Exterior Use. U.S. Department of Defense.

MIL-PRF-32550. Metal-Rich Primer. U.S. Department of Defense.

MIL-S-901. Shock Tests, H.I. (High-Impact) Shipboard Machinery, Equipment, and Systems, Requirements for. U.S. Department of Defense.

MIL-STD-108. Definitions of and Basic Requirements for Enclosures for Electric and Electronic Equipment. U.S. Department of Defense.

MIL-STD-889. Detail Specification: Dissimilar Metals. U.S. Department of Defense.

SAE J2360. Automotive Gear Lubricants for Commercial and Military Use. SAE International.

SSPC-SP 10. Near-White Metal Blast Cleaning. Association for Materials Protection and Performance.

UL 991. Tests for Safety-Related Controls Employing Solid-State Devices. Underwriters Laboratories.

A-2 PERFORMANCE REQUIREMENTS

(23)

A-2.1 General

Performance requirements shall be in accordance with ASME HST-1 and as specified in this Appendix.

A-2.2 Application

Metals susceptible to corrosion attack in a seawater environment shall be treated, plated, or painted to provide corrosion resistance. Assemblies containing dissimilar metals shall be protected against galvanic corrosion in accordance with MIL-DTL-917 and MIL-STD-889. If a metal is coated or plated, the coating or plating metal, rather than the base metal, shall be considered in metal-to-metal contact between parts that depend upon coating or plating for corrosion resistance.

When specified [see [para. A-6\(c\)](#)], hooks shall be zinc plated. Zinc plating shall be in accordance with ASTM B633, Type I, Class Fe/Zn12. The hook throat safety device shall be constructed of noncorrosive material or treated for corrosion resistance.

When specified [see [para. A-6\(d\)](#)], the load chain shall be protected from corrosion by zinc plating in accordance with ASTM B633, Type II, Class Fe/Zn.

The safeguarding against and procedure for detecting embrittlement of zinc coating shall be in accordance with ASTM A143/A143M.

A-2.3 Characteristics: Weight and Dimensions

Maximum weight and envelope dimensions of hoists shall be specified if important to the application [see [para. A-6\(e\)](#)].

A-2.4 Emergency Manual Operation

A-2.4.1 Handwheel. When specified [see [para. A-6\(f\)](#)], hoist shall be equipped with a handwheel attached to an extension of the electric motor shaft for emergency manual operation of the hoist. It shall be possible to declutch the handwheel when it is not in use. An interlock shall be provided to prevent operation of the hoist electrically while the handwheel is engaged. A pull of not more than 1 lb per 200 lb (0.45 kg per 90.7 kg) of total hoist load shall be required to initiate movement.

A-2.4.2 Hand Chain. The handwheel described in [para. A-2.4.1](#) shall be operated by a removable chain, which, when fitted, will have a drop of approximately 2 ft (0.61 m) less than the specified lift of the hoist.

A-2.5 Load Positioning Control

Hoist control systems shall vertically position a load to within $\pm\frac{1}{4}$ in. (± 6.4 mm).

A-2.6 Lubrication

Lubricants used shall be readily available and free of ozone depleting chemicals. Means shall be provided for lubrication of the hoist and trolley moving parts. Lubrication arrangements shall require infrequent attention. Where permanently lubricated bearings are used, means for external lubrication are not required. Exposed bearings shall be sealed or shielded. Lubricating oil shall be in accordance with SAE J2360, grade 80W90. Grease requirements shall be consistent with DOD-G-24508.

A-2.7 Painting

Paints and coatings shall be lead and chromate free. When specified (see [para. A-5.3.2](#)), exposed surfaces, except hooks, chains, and other wear surfaces, shall be cleaned, pretreated, and finish coated in accordance with method I as specified in [para. A-2.7.1](#). Method II (see [para. A-2.7.2](#)) may be used if method I is not specified.

A-2.7.1 Method I. Exposed surfaces, except hooks, chains, and other wear surfaces, shall be painted as specified herein. Before assembly, surfaces requiring painting shall be cleaned in accordance with SSPC-SP 10. Steel surfaces, except for corrosion-resistant steel, shall be coated with an inorganic zinc primer conforming to MIL-PRF-32550, applied at 3 mils to 5 mils dry film thickness (DFT). Prior to overcoating, residual deposits shall be removed by the manufacturer's recommended cleaning procedure. A coat of formula 150 that has been thinned with 1 Pt of thinner per gallon (1.25 dL of thinner per liter) shall be applied, in accordance with MIL-DTL-24441 and MIL-DTL-24441/20, at a wet film thickness of 3 mils. This shall be followed by a full coat of formula 151, in accordance with MIL-DTL-24441/21, applied at 2 mils to 4 mils DFT, and two coats of silicone alkyd enamel, in accordance with MIL-PRF-24635, applied at 1 mil to 2 mils DFT per coat. The first coat of enamel shall be applied when the formula 151 is in the tack stage. Other metals that are not inherently corrosion resistant, as defined in MIL-DTL-917, shall be processed (treated, plated, or painted) in accordance with MIL-DTL-917 to provide corrosion resistance.

A-2.7.2 Method II. Method II surface preparation and finish shall be contractor's standard commercial procedures. Paints and coatings shall be lead and chromate free.

A-2.8 Workmanship

The hoist shall withstand any operation specified herein without malfunction or component failure caused by faulty workmanship. Edges and surfaces exposed to operating and maintenance personnel shall be smooth and rounded so that a hazardous surface does not exist. See [Table A-2.8-1](#) for hook throat openings. Parts of the hoist, before and after painting, shall be clean and free of sand, rust, dirt, fins, pits, sprues, scale, and other harmful extraneous materials. Bolted connections shall use standard bolts and nuts. Self-locking nuts shall be allowed. Threads shall have full thread engagement.

A-2.9 Interchangeability

In no case shall parts be physically interchangeable or reversible unless such parts are also interchangeable or reversible with regard to function, performance, and strength. Component parts for the same hoist types from the same manufacturer shall be interchangeable to the greatest extent possible.

A-3 MECHANICAL REQUIREMENTS

A-3.1 Design Stresses

Maximum combined stress in component parts shall not exceed 35% of the tensile yield strength of the material for hoist operation at rated capacity. Combined stresses in component parts shall not exceed 70% of its tensile yield strength when the hoist is subjected to static or dynamic overload tests. For hoists requiring repair parts, all wear parts shall be readily accessible for replacement. For hoist operation, a pull of not more than 1 lb per 200 lb (0.45 kg per 90.7 kg) of total hoist load shall be exerted to initiate movement, and not more than 1 lb per 300 lb (0.45 kg per 136 kg) of total hoist load shall be required for manual operations of the trolley.

Table A-2.8-1
Hook Throat Openings

(23)

Hoist Rated Load, lb (kg)	Minimum Hook Throat Opening, in. (mm)
1,000 (453.6)	0.75 (19.05)
2,000 (907.2)	0.906 (23.01)
3,000 (1 360.8)	1.0 (25.4)
4,000 (1 814.4)	1.125 (28.575)
5,000 (2 268)	1.125 (28.575)
6,000 (2 721.6)	1.5 (38.1)
7,500 (3 401.9)	1.375 (34.925)
10,000 (4 535.9)	1.625 (41.275)
11,000 (4 989.5)	2.0 (50.8)
13,000 (5 896.7)	2.063 (52.4)
15,000 (6 803.9)	2.063 (52.4)
17,000 (7 711.1)	2.063 (52.4)
20,000 (9 071.8)	2.25 (57.15)
25,000 (11 339.8)	2.25 (57.15)
30,000 (13 607.8)	2.75 (69.85)
40,000 (18 143.7)	3.0 (76.2)

A-3.2 Load Hooks

(23)

A-3.2.1 General. Load hooks shall be of drop-forged heat-treated steel. Hooks shall be provided with a safety device. The safety device shall consist of a spring latch or swivel-type closure to bridge the throat opening and shall be an integral part of the hook. The swivel shall permit 360-deg rotation of the hook with full load without twisting the chain. Hook throat openings shall be in accordance with the dimensions shown in [Table A-2.8-1](#). The hook shall be clearly marked with manufacturer identification and allowable hook load or allowable hook load designator.

Positive means shall be provided to prevent the load hook from loosening due to rotation of the load. Load hooks shall be readily detachable from the load chain. Locking pins shall be provided to prevent accidental detachment of the hooks.

A-3.2.2 Range of Load Hooks. Load hooks for Type I, Type II, Type III, Type V, and Type VI hoists shall pick up a load with the hook anywhere within a radius of 3.5 ft (1.07 m) below the wheel without jamming or jumping the pockets of the load wheel.

Load hooks for Type IV hoists (with the arrangement specified in [para. A-3.7.3](#) and with the trolley oscillating about the wire rope on which it operates) shall be capable of picking up a load from any point within a 19-in. (482.6-mm) radius, from an imaginary perpendicular, from the point of hoist suspension to a horizontal plane 7 ft (2.1 m) below this point (an angle of approximately 15 deg).

A-3.3 Construction

Rotating shafts shall be supported in antifriction bearings or bushings or both and shall be enclosed against entry of foreign matter. Rotating and sliding surfaces shall be lubricated. Hoists shall operate through a temperature range of -20°F to 103°F (-29°C to 39.4°C) for a minimum of 3,000 cycles without a failure. Gears shall be totally enclosed in a readily accessible casing that will permit examination, servicing, and cleaning. Positive means shall be provided to prevent any component working loose. Hoist parts shall be readily accessible for servicing and replacement as required.

A-3.3.1 Load Chain. The chain shall provide a safety factor of at least five for the rated load based on the ultimate strength of the material.

A-3.3.2 Gearing. Gears shall be manufactured in accordance with AGMA 6034.

A-3.3.3 Overtravel Protection. The lift limiting device specified in ASME B30.16, paras. 16-1.2.13 and 16-1.2.14 shall protect against upper and lower limits of travel. Type I hoists shall not have these devices (see [para. A-4.2.4](#)).

A-3.3.4 Overload Protection. Mechanical overload limiting devices shall not be permitted in naval applications unless the hoist is provided with a mechanical load brake and the mechanical overload limiting device is not installed on the load side of the hoist.

- (23) **A-3.3.5 Load-Chain Container.** When specified, the hoist shall be equipped with a container attached to the hoist for receiving the chain as it is reeved in by the chain wheel. The container shall be located to prevent interference with the low headroom features of the hoist, when applicable.

A-3.3.6 Trolley Track. Trolley tracks for Type III and Type IV hoists shall be I-beam of the size and radius specified.

A-3.4 Type I Electric Chain Hoist, Lug Suspension, Double-Acting

A-3.4.1 Double-Acting Feature. The double-acting feature shall be obtained by arranging a load chain having two free ends to operate back and forth over a power-driven chain wheel. Either end of the chain, when fitted with a load hook, shall handle the load for which the hoist is rated. The hoist will not be required to handle load on both hooks simultaneously. Separation of the load chains, when hanging vertically, shall be a maximum to permit free passage of the empty and loaded hooks when traveling in the hoisting or lowering directions.

A-3.4.2 Control Stations. Controllers shall be operated by two pendant-type push-button stations separately suspended from the hoist. Push-button stations shall be connected in series, thus making it necessary that corresponding push buttons be depressed simultaneously at each station to move the load hooks in either direction. Length of one of the control cables shall be as specified [see [para. A-6\(g\)](#)]. The other cable shall be of a length equal to the lift of the hoist. Each push-button station shall be provided with indicating lights. These lights shall be arranged to indicate to the controls operator which push button has been depressed at any other station. Enclosure shall be spray tight.

A-3.5 Type II Electric Chain Hoist, Lug Suspension, Single-Acting

A-3.5.1 Control Stations. Control stations shall be pendant control type or bulkhead mounted as specified [see [para. A-6\(h\)](#)].

A-3.6 Type III Electric Chain Hoist, Parallel or Right Angle Geared or Plain Trolley Suspension

- (23) **A-3.6.1 Trolleys.** Trolleys shall be geared or plain, as specified [see [para. A-6\(i\)](#)].

A-3.6.1.1 Trolley Wheels. Trolleys shall be provided with at least four wheels. Trolley wheels shall be of ferrous material. Trolleys up to and including 3-ton capacity shall have wheels of solid or pressed steel with treads hardened to a minimum depth of 0.0202 in. (0.513 mm). For trolleys over a 3-ton capacity, wheels shall be of forged or solid steel with treads hardened to a minimum depth of 0.062 in. (1.575 mm). Trolley wheels shall have treads hardened to a minimum of 285 Brinell hardness number. Wheels shall be concentric within 0.030 in. (0.762 mm) and cast wheels shall be machined treads. Trolley wheel spacing shall be suitable for use on an applicable standard I-beam flange size. Means shall be provided to prevent the trolley wheel flanges from riding up onto the supporting beam.

A-3.6.1.2 Trolley Equalizers. Means shall be provided for distributing the hoist load equally into trolley side frames.

A-3.6.1.3 Trolley Track Clamps. Quick-acting track clamps shall be provided for locking fully loaded hoists to the track. Clamps shall be adjustable for wear and shall function equally well on curved or straight track. Clamps shall function without increasing the trolley wheel shaft or wheel bearing load, and in such a manner that the stresses resulting from locking shall be taken up by the trolley frame. Operation of the track clamps shall be with either a lever or a chain wheel equipped with hand chain. Hand pull required to set or release the track clamps shall not exceed 80 lb (36.3 kg). Chain drop from beam shall be approximately 2 ft (0.61 m) less than the specified lift of the hoist. When tested as specified (see [para. A-5](#)), track clamps shall not show signs of slipping or permanent deformation.

A-3.6.2 Cable Reel. An automatic, clock spring-type cable take-up reel for ceiling mounting shall be furnished for the hoist motor power supply cable.

A-3.6.3 Control Stations. Control stations shall be pendant control type or bulkhead mounted as specified [see [para. A-6\(h\)](#)].

A-3.7 Type IV Electric Chain Hoist, Two-Wheel Tandem Trolley Suspension

A-3.7.1 Load-Lifting Medium. Close link, coil-type load chains shall be the load-lifting medium.

A-3.7.2 Hoist Trolley. Trolleys shall operate on high-grade plow steel, constant tensioned wire rope, as specified [see para. A-6(j)]. The trolley shall not jump or fall from the wire rope under any condition. The trolley assembly shall be quickly removed from the rope for storage purposes. A hole shall be accessibly located at each end of the trolley structure to permit making a clevis connection, the clevis being located at the end of the ropes used to tow the trolley along the wire suspension. The trolley structure around the hole shall be reinforced so that pull on the clevis connection will not cause any permanent distortion.

A-3.7.3 Trolley Connection to Hoist. Trolleys shall be pin connected to the hoist with a degree of freedom to permit the hoist to swing forward or backward in the direction of trolley travel. Hoist swing angle shall be limited by stops on the trolley to prevent the hoist from contacting the trolley wire suspension.

A-3.7.4 Control Station. Motor controllers shall be operated from a pendant suspended, retractable, three element push-button station. The retractable feature shall be provided through use of a clock spring-actuated cable reel, which shall be included as part of the motor control enclosure. Push-button enclosure shall be fitted with a handle to enable the hoist operator to conveniently hold the push-button station at proper operating height.

Enclosure shall be fitted with an eyebolt or other means for securing a reach rope, which will be used to haul the control station down to the operator. When three elements are required, the push buttons shall be legibly and permanently marked "HOIST," "LOWER," and "EMERGENCY RUN" to indicate hoist operation. The function of the "EMERGENCY RUN" push button shall be to bypass the thermal overload device.

A-3.8 Type V Electric Chain Hoist, Hook Suspension

A-3.8.1 Mounting. Mounting hooks shall have a spring-loaded-type safety gate resting against the tip of the hook. The safety gate shall be of sufficient strength to withstand a pull against the safety gate equal to the weight of the fully loaded hoist.

A-3.8.2 Control Stations. Control stations shall be pendant control type or bulkhead mounted as specified [see para. A-6(h)].

A-3.9 Type VI, Electric Chain Hoist, Powered Trolley Suspension

A-3.9.1 Hoist Trolley Connection. Hoists shall be suspended from their trolleys by means of a pin connection that will permit the hoist body to swing a maximum of 15 deg fore and aft in the direction of trolley travel. When the hoist is allowed to swing, it shall be so restrained that no part of the hoist will contact the load lifting medium. Trolley motor and gearing, as specified herein, shall be attached to the hoist so as to permit the front of the hoist to approach the end of the trolley track with the intent of bringing the hanging load chain as close to the end of the track as practicable.

A-3.9.2 Load Attachment Device. The lifting end of the load chain shall be fitted with a swivel connection device.

A-3.9.3 Power-Operated Trolley. Trolleys shall be positive traversing, shall operate on a standard I-beam, and shall traverse the hoist along the track through a speed of 0 ft/min to 40 ft/min (0 m/min to 12.2 m/min) with rated load. Trolleys shall drive the hoist with rated load along a track tilted and inclined ± 15 deg from horizontal. For this requirement, overloading of the trolley drive motor up to 50% of its rated capacity for 20 min during ship rolling and pitching conditions will be acceptable.

A-3.9.4 Positive Traversing Feature. To provide positive traversing of the hoist, the trolley shall be equipped with a sprocket, rotating in vertical plane, and driven by the trolley motor. The sprocket shall engage a strip of roller-type chain attached to the flange of the I-beam trolley track. The roller chain shall be of the length as specified and shall be suitable for tack welding to the flange of the I-beam. This arrangement shall ensure that the hoist and trolley, when stopped, will hold its position on the trolley track. A brake, attached to the sprocket shaft or non-overhauling worm gears, shall be provided.

A-3.9.5 Hoist and Trolley Control Station. Hoists and trolleys shall be operated by a pendant-type handheld or bulkhead-mounted control station, as specified. Control station design shall incorporate a four-element push-button circuit with the dead man feature (push buttons automatically return to "OFF" position when released). Two push buttons shall be marked "Hoist" and "Lower" for hoisting and lowering operations, and the other two push buttons shall be identified with arrows (" $<$ " " $>$ ") and color coded to indicate direction of trolley operation. Corresponding color-coded arrows shall be affixed to the hoist and shall be visible from all operating positions of the hoist. If the control station is bulkhead mounted, the control leads shall be fed from a cable reel as specified herein (see para. A-3.6.2).

A-3.9.6 Headroom. Headroom dimensions shall be as specified (see para. A-5.3.2). Headroom is measured from the underside of the trolley track flange to the lowest point of the load attachment device (see para. A-3.9.2) in its raised position or to the saddle of the load hook. (23)

(23) A-3.10 Chain Guides

Load chain wheels shall be provided with at least four pockets accurately shaped to fit the links of the load chain, which shall operate freely and smoothly over the load wheel. Enclosed chain guides shall be provided to ensure that the hoist load chain enters the sprocket in the proper position to prevent misalignment or jamming of the hoist load chain and sprocket. These guides, if bolted on, shall have means to prevent loosening under vibration. The load shaft may be integral with or rigidly connected to the load chain wheel. The wheel shall not be welded to the load shaft.

A-3.11 Material

Material used on hoists and their components shall be of sufficient hardness and strength to withstand intended use and applicable tests.

A-3.11.1 Recycled, Recovered, or Environmentally Preferable Materials. Recycled, recovered (see [para. A-1.3](#)), or environmentally preferable materials should be used to the maximum extent possible provided that the material meets or exceeds the operational and maintenance requirements and promotes economically advantageous life cycle costs.

A-3.11.2 Prohibited Material. Cadmium, asbestos, beryllium, brittle materials (see [para. A-1.3](#)), and magnesium or magnesium-based alloys (except steel or aluminum alloys that contain less than 0.5% magnesium) shall not be used unless otherwise specified. Welded aluminum 6061-T6, 2XXX, and 7XXX material shall not be used.

A-3.11.3 Cast Iron. Cast iron shall not be used for load-bearing parts. Cast iron for nonload-bearing parts shall be in accordance with ASTM A48/A48M, Class 35 or better.

A-3.11.4 Aluminum. Aluminum castings, if used, shall be in accordance with ASTM B26/B26M.

A-4 ELECTRICAL**(23) A-4.1 General**

A-4.1.1 Compliance With MIL-DTL-917. Motors, controllers, brakes, and power supply cable shall be in accordance with MIL-DTL-917 and, when specified [see [para. A-6\(k\)](#)], shall withstand Grade A shock (see [para. A-5.1.1](#)). If shock testing is specified, the power supply cable shall be in accordance with MIL-DTL-24643.

A-4.1.2 Hazardous Locations. When hoists are used in hazardous locations as defined by MIL-DTL-917 or other special codes, modifications or additional safety precautions not covered by this Appendix may be required.

A-4.2 Electrical Equipment Characteristics

A-4.2.1 Motors. Temperature rise of motors shall be in accordance with MIL-DTL-917 for the class of insulation and enclosure used.

A-4.2.2 Hoist Brakes. Hoists shall be equipped with an electric brake and, except for Type I hoists, a load brake. The load brake shall be provided to prevent operation of the hoist in the lower direction unless power is applied, and it shall be independent of the electric brake. The electric brake shall stop and safely hold 150% of the hoist rated load at any operating speed. The electric brake shall hold a static load equal to 200% of the hoist rating.

When specified [see [para. A-6\(l\)](#)], manual release of the electric brake shall be provided to permit manual operation by the handwheel as specified herein (see [para. A-2.4.1](#)).

A-4.2.3 Operator's Control Station. Push-button controls shall be momentary contact type (spring return to the "OFF" position when released). Push-button controls shall be fully enclosed in a shock-resistant, watertight case, with rounded corners. Enclosure shall be watertight.

A-4.2.4 Lower Limit Switch. A lower limit switch shall be provided on Type I hoists to prevent the load hook from over travel. The switch shall be arranged to automatically stop the hoist motor and apply the motor brake when the hook reaches its lower travel limit position.

A-4.2.5 Control Enclosures. Control enclosures, unless otherwise specified [see [para. A-6\(m\)](#)], shall be NEMA Type 12 in accordance with MIL-DTL-917.

A-4.2.6 Speed Governor. When specified [see [para. A-6\(n\)](#)], Type I hoists shall be equipped with a centrifugal-type speed governor to limit lowering speed to a maximum of 80 ft/min (24.4 m/min). Stopping of the hoist shall be accomplished by the electric brake specified herein (see [para. A-4.2.2](#)).

Table A-4.2.7-1
Electromagnetic Environment

Frequency Range	Units	
Communications 250 kHz to 30 MHz	V/m 50	
Radar	Average, mW/cm ²	Peak, mW/cm ²
200 MHz to 225 MHz	7	1,600
400 MHz to 450 MHz	5	300
850 MHz to 942 MHz	12	400
1.215 GHz to 1.365 GHz	3	3,900
2.7 GHz to 3.7 GHz	78	32,000
5.4 GHz to 5.9 GHz	2	1,400
16.3 GHz to 33 GHz	1	1,000

A-4.2.7 Electromagnetic Interference and Compatibility. Hoist electrical equipment shall operate satisfactorily under the electromagnetic environment specified in [Table A-4.2.7-1](#).

A-4.2.8 Availability, Reliability, and Maintainability. The minimum acceptable inherent availability, A_i , of the hoist shall be 0.90. The hoist shall operate for an average period of 3,000 continuous cycles without failure (this value of 3,000 mean cycles between failure is equivalent to 90 days of normal ship's operation without hoist failure). Routine corrective maintenance at the organizational level shall be accomplished by replacing complete assemblies and subassemblies. Mean time to repair for the hoist shall be 4 hr. Not less than 95% of all corrective maintenance actions shall require not greater than 10 hr to complete. Reliability and maintainability are defined in MIL-HDBK-781. (23)

A-5 TESTING, MARKING, AND DATA

A-5.1 Testing

A-5.1.1 Shock. When specified, hoists shall undergo the shock test in accordance with the requirements of MIL-DTL-901. Resilient mountings shall not be used. Trolley hoists shall be secured only by their own track clamps. Trolley hoists and hook suspension hoists shall be mounted in their normal position. Type V hoists shall be tested in the stowed position (horizontal attitude), constrained (not fastened) to prevent lateral movement, and clamped or strapped to resist vertical movement and to prevent the test unit from becoming a missile hazard to test personnel. Hoists shall have the load hook retracted for the test. The chain shall be looped in bights not to exceed 2 ft (0.61 m) and secured in or lashed to the load hook during the test. Test fixture for mounting the hoist shall conform, as applicable, to the deck-mounted, platform-mounted, or bulkhead-mounted figures shown in MIL-DTL-901. A request to deviate from the test fixture for mounting hoists differing from those specified shall be submitted to the contracting activity. Shock tests shall comply with the requirements as specified. Separation of component parts of the hoist during the test or evidence of permanent deformation of the hoist during the post-shock inspection shall constitute failure of the hoist for shock Grade A equipment. Separation of component parts from the hoist during the test shall constitute failure of the hoist for shock Grade B equipment. Failure of the hoist shall be cause for rejection of the lot. Following successful completion of a shock test, the hoist shall be subjected to the tests as shown in [Table A-4.2.7-1](#). (23)

A-5.1.2 Load. Hoists with overload protection devices shall demonstrate the hoists' ability to lift and hold a load equal to $1\frac{1}{2}$ times its rated capacity without slippage. (23)

A-5.1.2.1 Static Load. Hoists shall support a static load of twice the maximum rated capacity for a period of 10 min. This load shall be suspended with the hoist load chain extended to the limit of the hoist's rated lift height. This extension may be changed to a minimum of 1 ft (0.3 m), provided the contractor demonstrates that the entire length of chain is capable of 200% load. The suspended test load shall be held by the hoist brake. Evidence of failure or permanent deformation of hoist parts shall be cause for rejection of the lot.

A-5.1.2.2 Dynamic Load. Hoists shall be loaded to 150% of rated capacity and operated by hoisting and lowering the test load through the full operating range. Trolley-type hoists shall be operated back and forth over a section of track 8 ft (2.4 m) or more in length with the 150% load in suspension. This test shall be performed 10 times. Hoists and trolleys shall

operate satisfactorily, and brakes shall exhibit no sign of slippage. Evidence of failure, permanent deformation, or excessive wear of hoist parts shall be cause for rejection of the lot.

A-5.1.3 Operating. Hoists shall be tested as follows to determine that they are satisfactory for operation with rated loads:

(a) *Hoisting Speed.* Hoists shall be operated for approximately 90% of lift height, to verify conformance with the hoisting speed requirements.

(b) *Lowering Speed.* Hoist load hooks shall be lowered at a maximum speed of 80 ft/min (24.4 m/min) and timed to determine conformance with the speed governor requirements.

(c) *Travel Limit.* Hoists shall be operated in the up and down directions so as to engage the limit switches to demonstrate hoist ability to prevent load hook overtravel.

(d) *Load Positioning Control.* Hoists shall demonstrate their capability to accurately position a load. The test shall be conducted by establishing a reference height and then jogging the load to a position $\pm \frac{1}{4}$ in. (± 6.4 mm) above and below the reference height. Repeat each test at least six times. Each positioning shall be accomplished by energizing the motor no more than six times.

(e) *Performance.* Hoists shall be continuously operated at maximum speed [80 ft/sec (24.4 m/s)] through approximately 90% of lift height for a period of not less than 30 min. During this test, the hoist shall operate satisfactorily without any indication of malfunction.

A-5.1.4 Manual Operation. Hoists shall be tested to demonstrate

(a) the ability to lift and lower through the full hoisting range a rated load by means of the handwheel arrangement

(b) the interlock prevents electrical operation

A-5.1.5 Electromagnetic Interference Measurements. Electromagnetic interference testing shall be done in accordance with UL 991.

A-5.1.6 Geared Trolley Traverse. On Type III geared trolley hoists, a pull of not more than 1 lb per 200 lb (0.45 kg per 90.7 kg) of total hoist load shall be exerted on the hand chain to initiate movement of the hoist load, and a pull of not more than 1 lb per 300 lb (0.45 kg per 136.1 kg) to initiate hoist and trolley movement.

A-5.1.7 Track Clamp. Track clamps on Type III hoists shall be tested by subjecting the loaded hoist to a pull equal to one-third of the rated capacity of the hoist. The pull shall be exerted in either direction parallel to the trolley tracks. Clamps shall hold the loaded hoist from moving in either direction when the trolley track is in a horizontal position. Track clamps shall have no sign of slipping or of permanent deformation.

A-5.1.8 Fleet Angle. Hoists shall demonstrate their ability to pick up a load with the hook attached to the load at 3.5 ft (1.07 m) out from an imaginary perpendicular 7 ft (2.1 m) below the hoist. Chain hoists shall accomplish this without the chain jamming or jumping the pockets of the load wheel. The lift shall be conducted four times, once forward, once aft, and once on each side of the hoist.

A-5.1.9 Trolley Test for Type IV Hoist. The hoist trolley shall be tested under the following conditions to demonstrate that it is capable of maintaining its positioning on the wire rope on which it operates:

(a) with the hoist attached to the trolley and load hook empty, oscillate the suspended hoist ten times about the axis of the wire rope through an included angle of 70 deg (35 deg on either side).

(b) repeat (a) with rated load.

(c) repeat (a) with 150% rated load.

(d) demonstrate the hoist capability to pick up a load in any direction that is at an angle of 15 deg from the point of hoist suspension to a perpendicular, from the same point on the hoist (see para. A-3.2.2).

(e) *Plain Trolley Test.* The pull required to move the capacity-loaded hoist (plain trolley suspension) along a straight portion of track shall be determined by attaching a wire rope or cord to the trolley so that the pull is exerted parallel to the track, and then over a sheave hanging from the track at a reasonable distance from the trolley, and measuring the required pull by means of weights or spring balance attached to cable or cord. Failure to comply with the requirements for maximum pull to traverse the hoist shall constitute failure of this test.

(f) *Geared Trolley Test.* The pull required on geared trolley hand chain to move a capacity-loaded hoist (gear trolley suspension) along a straight portion of track shall be determined by attaching weights or a spring balance to the hand chain. Failure to comply with the requirements for maximum pull to traverse the hoist shall constitute failure of this test.

(g) *Hand Operation.* Type III, Type IV, and Type VI hoists and trolleys shall be operated by hand on straight and curved track with rated load. A pull of not more than 1 lb per 200 lb (0.45 kg per 90.7 kg) of hoist load shall be required to initiate movement, and no more than 1 lb per 300 lb (0.45 kg per 136.1 kg) of hoist load shall be required to sustain this load (without assistance from the hook) without any distortion and shall operate properly upon removal of the load.

A-5.1.10 Mounting Hook for Type V Hoist. The safety gate of the mounting hook shall demonstrate its ability to hold a load equal to the weight of the fully loaded hoist. This hook shall be attached to a padeye of sufficient strength, and a cable shall be rigged through the hook and safety gate to a load equal to the weight of the fully loaded hoist. The safety gate shall hold this load (without assistance from the hook) without any distortion and shall operate properly upon removal of the load.

A-5.1.11 Trolley for Type VI Hoist. Powered trolley hoists shall be subjected to the following tests to determine capability of trolley operation:

(a) *Traversing Speed Test.* The power-operated trolley shall traverse the hoist with rated load along a horizontal trolley track, simulating a ship at an even keel to verify compliance with the traversing speed specified.

(b) *Trolley Drive Test (Rolling Conditions).* The trolley shall traverse the loaded hoist on a trolley track inclined at an angle of 15 deg from a horizontal centerline to verify satisfactory operation during ship rolling. The trolley will not be required to operate at a specified speed on this incline but shall move along steadily.

(c) *Trolley Brake Test.* With the hoist fully loaded and the trolley on an inclined and tilted track at an angle of 15 deg, it shall be demonstrated that when stopped, the trolley shall maintain its position on the track by means of the braking arrangement specified in [para. A-3.9.4](#).

A-5.1.12 Endurance. Hoists shall be subjected to 3,000 cycles of continuous operation (see [para. A-1.3](#)). After completion of the above tests, gears, chain, bearings, chain sprockets, brakes, and other wearing parts shall be examined for excessive wear (see [para. A-1.3](#)). A cycle of operation is defined as the lifting and lowering through the full hoisting range at a rated load at the specified lifting and lowering speeds. (23)

A-5.1.13 Vibration. When specified, hoists shall undergo Type II vibration testing in accordance with the requirements of MIL-STD-167-1. All hoist components shall operate without degradation and shall not come loose when subjected to vibration. (23)

A-5.2 Marking: Identification (23)

In addition to the requirements in ASME B30.16, Section 16-1.1, hoists shall be identified with the following:

- (a) hoist weight and shock grade, as applicable
- (b) type, as applicable
- (c) rated load
- (d) ASME HST-1, Nonmandatory Appendix A
- (e) national stock number (NSN), if established
- (f) contract or order number
- (g) date of manufacture

A-5.3 Data: Technical Manuals (23)

When specified [see [para. A-6\(f\)](#)], the manufacturer shall prepare technical manuals in accordance with the data ordering documents and include the following:

- (a) complete list of material
- (b) identification of each component for replacement
- (c) final drawings

A-6 TYPICAL HOIST INQUIRY DATA (23)

In addition to the typical hoist inquiry data of ASME HST-1, acquisition documents shall specify the following:

- (a) compliance to ASME HST-1, [Nonmandatory Appendix A](#), if required
- (b) type of hoist required (see [para. A-1.2](#))
- (c) whether zinc coating of hooks is required (see [para. A-2.2](#))
- (d) whether zinc plating is required for load chain (see [para. A-2.2](#))
- (e) maximum weight and dimensions required (see [para. A-2.3](#))
- (f) whether manual operation is required (see [para. A-2.4.1](#))
- (g) length of control cable required for Type I hoist (see [para. A-3.4.2](#))
- (h) type of control station, if other than pendant control (see [paras. A-3.5.1, A-3.6.3, and A-3.8.2](#))
- (i) geared or plain trolley on Type III hoists (see [para. A-3.6.1](#))
- (j) Type IV hoist trolley requirements (see [para. A-3.7.2](#))
 - (1) size and type of wire rope required

- (2) speed and acceleration rates
- (3) load pull on clevis connection
- (k) whether shock testing is required, and if shock testing is required, whether hoist shall meet shock Grade A or Grade B (see [para. A-4.1.1](#))
- (l) whether manual brake release is required (see [para. A-4.2.2](#))
- (m) control enclosures if other than specified (see [para. A-4.2.5](#))
- (n) whether speed governor is required (see [para. A-4.2.6](#))
- (o) whether technical manual is required (see [para. A-5.3](#))
- (p) electric brake requirements (see [para. A-4.2.2](#))
- (q) hoisting speed (see [Section 1-1.6](#))
- (r) height of lift (see [para. A-5.1.2.1](#))
- (s) whether trolley wheel spacing is other than specified (see [para. A-3.6.1.1](#))
- (t) length of load chain (see [para. A-3.9.4](#))
- (u) whether reliability and maintainability tests are required (see [para. A-4.2.8](#))

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